Some topos-theoretic principles for syntactic learning

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Tying syntax and semantics:

- Starting remarks:
 - → Computers store <u>finite sequences of symbols</u> and process them using <u>formal rules</u>.
 - \rightarrow In other words, computers are syntactic machines, dealing with formal languages.
- Problem:
 - \rightarrow Syntax has <u>no structure</u> and <u>no directions</u>. It can go anywhere.
 - \rightarrow So, syntax needs a guide.
- The experience of natural and mathematical languages:
 - → Words are spoken and written in an highly structured way, in order to mean something, to make sense.
 - → For mathematicians, formal languages describe <u>mathematical structures</u>. But, in order to <u>discover</u> these <u>structures</u>, <u>study them</u> and <u>derive properties</u> in a formal way,

they <u>need</u> to imagine and consider <u>"concrete" instances</u> of these structures, i.e. "<u>models</u>".

→ Tarski has defined "syntax" as formalization of "theories", and "semantics" as their incarnation in "models".

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Semantics and topology:

- Experience and intuitions of mathematicians:
 - → Mathematicians experience that what they can really understand in mathematics is geometry and topology (the science of forms).
 - → For instance, number theory is especially difficult because it is a priori not geometric.

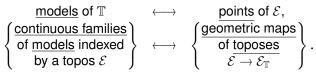
But huge progress was made in number theory when,

thanks to abstraction, it could be studied with topological ideas.

- \rightarrow <u>From the 1960</u>'s to present,
 - different <u>mathematicians</u> and <u>theoretical computer scientists</u> expressed the idea that "<u>semantic information</u>" should <u>incarnate</u> in "topological forms".
- Topology as the science of toposes:
 - \rightarrow Around 1960, Grothendieck introduced the notion of "topos" as the most general mathematical concept of "space" which still allows to <u>define</u> and study
 - points and continuous maps,
 - subspaces, their intersections and their unions,
 - images and pull-backs of subspaces by continuous maps,
 - global invariants (as cohomology and homotopy).

Semantics and toposes:

- A double theorem established in the 1970's shows:
 - $\label{eq:thermalized} \begin{array}{l} \rightarrow \mbox{There is a very general notion of "formalized language",} \\ \mbox{the notion of "first-order geometric theory" \mathbb{T},} \\ \mbox{such that, for any such theory \mathbb{T},} \\ \mbox{its semantics (in the sense of Tarski)} \\ \mbox{is incarnated by a (unique) topos $\mathcal{E}_{\mathbb{T}}$:} \end{array}$



- \rightarrow Conversely, any topos \mathcal{E} incarnates the semantics of infinitely many such theories \mathbb{T} , i.e. $\mathcal{E} \cong \mathcal{E}_{\mathbb{T}}$.
- A semantic principle for guiding syntactic processing: Work with <u>theories</u> \mathbb{T} , only using processes which are <u>defined</u> in terms of associated toposes $\mathcal{E}_{\mathbb{T}}$ and geometric maps $\mathcal{E}^{\mathcal{T}} \to \mathcal{E}$ relating them.

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Elaboration of appropriate description languages:

- <u>Before</u> even thinking about how to <u>process</u> representations of some type of elements of reality (e.g. images), it is needed to <u>elaborate</u> an appropriate formal description language T.
 - \rightarrow It seems that this preliminary step

is often overlooked, whereas it is most important.

- Such a formal description language necessarily consists in a vocabulary Σ and a list of axioms (= grammar rules).
- The vocabulary has to be chosen so that
 - it is rich enough to allow

the expression of distinctions and differences,

it is <u>not too rich</u>,

so that it expresses analogies and shared identities,

and naturally leads to the discovery of natural laws.

• The <u>axioms</u> (expressing natural laws) should be infered from particular instances, thanks to the chosen vocabulary.

Axiom systems and topology:

• A <u>theorem</u> (established in 2008 by O. Caramello) shows that any <u>equivalence of toposes</u> $\mathcal{E} \cong \mathcal{E}_{\mathbb{T}}$ induces a one-to-one correspondence

$$\left\{ \underbrace{subtoposes}_{\mathcal{E}_1 \hookrightarrow \mathcal{E}} \right\} \longleftrightarrow \left\{ \begin{array}{c} \underbrace{geometric theories}_{deduced from \mathbb{T}} \mathbf{b} \\ \underbrace{adding new axioms}_{(in the same vocabulary)} \end{array} \right\}$$

- In particular, adding axioms to a vocabulary Σ to define a theory \mathbb{T} amonts to define a subtopos $\mathcal{E}_{\mathbb{T}} \hookrightarrow \mathcal{E}_{\Sigma}$.
- If $\mathcal{E} \cong \mathcal{E}_{\mathbb{T}}$ and $\mathcal{E}' \cong \mathcal{E}_{\mathbb{T}'}$, any <u>geometric map</u> $f : \mathcal{E}' \longrightarrow \mathcal{E}$ induces two maps

$$\begin{cases} f_*: (\mathcal{E}'_1 \hookrightarrow \mathcal{E}') & \longmapsto & (f_*\mathcal{E}'_1 \hookrightarrow \mathcal{E}), \\ f^{-1}: (\mathcal{E}_1 \hookrightarrow \mathcal{E}) & \longmapsto & (f^{-1}\mathcal{E}_1 \hookrightarrow \mathcal{E}'), \end{cases}$$

and so two processes of transformation of theories

$$\left\{ \begin{array}{c} \text{systems of} \\ \underline{\text{extra axioms}} \\ \overline{\text{added to } \mathbb{T}'} \end{array} \right\} \quad \stackrel{f_*}{\underset{f^{-1}}{\longleftarrow}} \quad \left\{ \begin{array}{c} \text{systems of} \\ \underline{\text{extra axioms}} \\ \overline{\text{added to } \mathbb{T}} \end{array} \right\}$$

Formal application of a description vocabulary:

- Suppose we are given elements of reality *E_i*, *i* ∈ *I*, which we feel belong to a natural family.
- Suppose we are able to <u>partially represent</u> each \mathcal{E}_i , by identifying some components and some <u>relations</u> between them, taking the form of a (finitely presented) "category"

(consisting in components, relations between pairs of components and a law of composition of relations).

• The <u>fact</u> that all \mathcal{E}_i 's are felt to belong to a <u>family</u> should <u>translate</u> into the definition of a joint vocabulary Σ allowing to give names to the <u>components</u> and <u>relations</u> of the <u>representations</u> \mathcal{C}_i 's, in the form of "naming functors"

$$\overline{N_i}: \mathcal{C}_i \longrightarrow \mathcal{C}_{\Sigma}$$

to the "syntactic category" C_{Σ} of Σ , whose components and relations consist in the words of Σ and the sentences in these words.

A geometric process of inductive reasoning:

- We need more geometric facts from topos theory:
 - Any (small) <u>category</u> C defines a topos C.
 The subtoposes C
 _J → C are indexed by so-called "topologies" J on C.
 - (2) Each C_J can be considered as a completion of C, so that the corresponding "topology" J on C can be called an "extrapolation principle" or "interpretation system".

3) If
$$\Sigma$$
 is a vocabulary, \mathcal{E}_{Σ} is a subtopos $\mathcal{E}_{\Sigma} \hookrightarrow \widehat{\mathcal{C}}_{\Sigma}$

and systems of extra axioms correspond to smaller subtoposes $\mathcal{E}_{\mathbb{T}} \hookrightarrow \widehat{\mathcal{C}}_{\Sigma}$.

(4) Any <u>functor</u> $N: \mathcal{C}' \to \mathcal{C}$ defines a geometric map $\widehat{\mathcal{C}}' \longrightarrow \widehat{\mathcal{C}}$.

Formal inductive reasoning:

Naming functors $N_i : C_i \to C_{\Sigma}$ define geometric maps $\widehat{C}_i \to \widehat{C}_{\Sigma}$. We look for a minimal system of axioms on the vocabulary Σ , defining

$$\mathcal{E}_{\mathbb{T}} \longrightarrow \widehat{\mathcal{C}}_{\Sigma}$$

 $(\widehat{\mathcal{C}}_i)_{J_i} \longrightarrow \widehat{\mathcal{C}}_i$

are meaningful representations of $\hat{\mathcal{E}}_i$, in the sense that all points of $(\hat{\mathcal{C}}_i)_{J_i}$ make sense in the context of each element of reality \mathcal{E}_i .

such that the subtoposes defined by pull-back

The geometric process of formation of singular descriptions:

• Suppose the previous "formal inductive reasoning" process has allowed to define a system \mathbb{T} of axioms on the vocabulary Σ , defining a subtopos $\mathcal{E}_{\mathbb{T}} \hookrightarrow \widehat{\mathcal{C}}_{\Sigma}$

and, by pull-back through the naming functors $N_i : C_i \to C_{\Sigma}$, some "meaningful representations"

$$(\widehat{\mathcal{C}}_i)_{J_i} \longrightarrow \widehat{\mathcal{C}}_i$$

of the elements of reality \mathcal{E}_i 's.

 Induced linguistic descriptions: Each induced geometric map

$$N_i: (\widehat{\mathcal{C}}_i)_{J_i} \longrightarrow \mathcal{E}_{\mathbb{T}}$$

has an image which is a subtopos

$$\overline{\mathrm{Im}(N_i)} = \mathcal{E}_{\mathbb{T}_i} \hookrightarrow \mathcal{E}_{\mathbb{T}}$$

necessarily <u>associated</u> to a theory \mathbb{T}_i deduced from \mathbb{T}

by adding a system of extra axioms.

Each such \mathbb{T}_i can be called a particular linguistic description of the element of reality \mathcal{E}_i

in the joint description language \mathbb{T} .

A general form of geometric information extraction:

• Suppose we have elaborated an appropriate formal description language \mathbb{T} for a family of elements of reality $\mathcal{E}_i, i \in I$, represented by subtoposes $\mathcal{E}_{\mathbb{T}_i} \hookrightarrow \mathcal{E}_{\mathbb{T}}$.

• Suppose we would want to <u>extract</u> from these representations some type of information phrased in a language \mathbb{T}' . So we need a geometric process for transforming

 $\overline{\{\text{subtoposes of } \mathcal{E}_{\mathbb{T}}\}} \longrightarrow \{\text{subtoposes of } \mathcal{E}_{\mathbb{T}'}\}.$

• It could take the form of a chain of geometric maps

